

PUMA 400

Powerful, Heavy Duty Turning Center



PUMA 400

The PUMA 400 series turning centers are without a doubt the most powerful machines in their class. High metal removal rates, along with rapid positioning and fast bi-directional turret indexing, guarantee unmatched cycle times when real cutting is essential.



Massive yet responsive turning centers without compromise. The most powerful machines in their class.



Main Spindle



Main Spindle

The headstock casting is made of Meehanite and ribbed on the outside to increase the surface area for better heat dissipation. The headstock and main spindle are manufactured in a temperature controlled environment then assembled and tested in our clean room. Double row of cylindrical roller bearings and duplex angular contact ball bearings, P4 class of the spindle ensure the highest rigidity and efficiency to transmit motor power to the end.

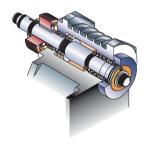
Max. spindle speed

1500 r/min (PUMA 400 C /MC/ LC / LMC / XLC / XLMC)

Motor (30 min)

37 kW (49.6 Hp) (PUMA 400 C/MC/LC/LMC/XLC/XLMC)

Main Spindle Drive



The high-torque spindle motor provides power for heavy stock removal, greatly reducing the number of roughing passes required. For 3 axis milling models, the motor is a spindle servo type controlling both the spindle in 2axis mode and full contouring C-axis in the 3axis mode. Switching between the two modes is nearly instantaneous.



Isolated Gear Box (DI Gear Box)

Power is delivered to the spindle through a two speed gearbox allowing high spindle speeds as well as powerful low end torque. The gearbox and spindle motor are isolated from the spindle, eliminating transfer of heat and vibration.

PUMA 400 A/B/C/LA/LB/LC/XLA/ XLB/XLC std.



BF Gear Box



Heavy cutting enabled with 2-step Baruffaldi Gearbox (standard), which is equipped with double bearings at the pulley shaft to enhance durability. The high precision BF Gearbox reduces noise at high speed. The gearbox and motor are separated from the spindle to isolate vibration, further enhancing working accuracy.

PUMA 400MC/LMC/XLMC std.

PUMA 400A/LA/XLA/B/LB/XLB/C/LC/XLC/MA/LMA/XLMA/MB/LMB/XLMB opt



Turret



Fast Turret Indexing

The large 12 and 10 station heavy duty turret features a large diameter Curvic coupling and hydraulic clamp force. The heavy duty design provides unsurpassed rigidity for heavy stock removal, fine surface finishes, long boring bar overhang ratios, and extended tool life. Turret rotation, deceleration and clamp are all controlled by a reliable high torque-hydraulic index motor. Unclamp and rotation are virtually simultaneous. Turret indexing is non-stop bidirectional with a 0.25 second next station index time. Turning tools are securely attached to the turret by wedge clamps.

Index time (1-station swivel)

0.25 s

No. of tool station

12 stations*

* In case of PUMA 400 B/C: 10 stations

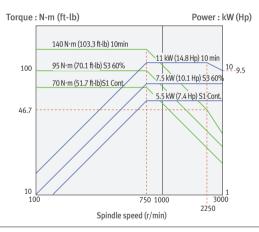
Preci-Flex Ready Rotary Tools

Preci-Flex ready rotary tool holders are available on the milling versions. Preci-Flex is a tooling system utilizes the existing ER collet taper in the rotary holders. The spindle face is precision ground relative to the taper and there are four drilled and tapped holders in this face. The Preci-Flex adapters locate on both the taper and the spindle face for maximum rigidity.



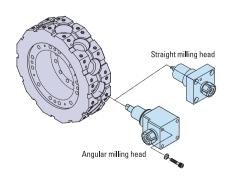
Rotary tool power-torque diagram

PUMA 400M / 400LM / 400XLM [7.5 kW(10.1 Hp) / 30min]



BMT Milling Turret

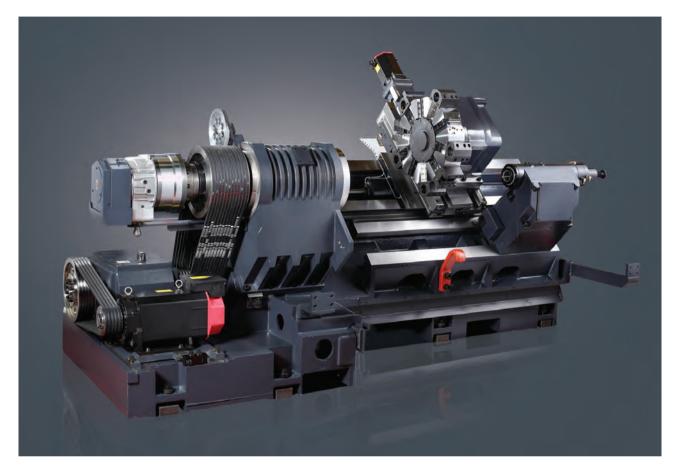
12 tool stations turret (BMT55P) make it possible to complete complicated parts requiring many tools in just one set-up. Reliable servo driven turrets reduce the total cycle time required to machine parts.





Bed and Way Construction

Doosan Infracore precision machine tools are internationally known for their durability, rigidity and high accuracy. Only well proven and time tested manufacturing techniques can produce machines of this quality.



The PUMA 400 series is a true 45 degree slant bed design. The bed is a one piece casting with both the saddle and tailstock guideways in the same plane to eliminate thermal distortion. The heavily ribbed torque tube design prevents twisting and deformation. Fine grain Meehanite processed cast iron is used because of its excellent dampening characteristics. This ensures high rigidity with no deformation during heavy cutting. The slant angle allows for easy loading, changing and inspection of tools. All guideways are wide wrap-around rectangular type for un-surpassed long-term rigidity and accuracy. The guideways are widely spaced to ensure stability and fully protected. Each guide-way is induction hardened and precision ground. A fluroplastic resin, Rulon® 142, is bonded to the mating way surfaces, for its wear and friction characteristics and then hand scraped for a perfect fit and center height. Optional long bed enables extra-long shaft machining.

Rapid Traverse

X-axis

16 m/min (629.9 ipm)

Z-axis

20 m/min (787.4 ipm) (PUMA 400A/B/C/MA/MB/MC)

18 m/min (708.7 ipm) (PUMA 400LA/LB/LC/LMA/LMB/LMC)

10 m/min (393.7 ipm) (PUMA 400XLA/XLB/XLC/XLMA/XLMB/XLMC)







Scraping of Slideway

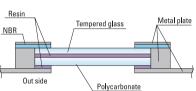
Outstanding rigidity for high feedrates

Ergonomic Design

Double-Paneled Safety Window



The operator safety can be enhanced through the front door with its shock absorbing laminated glass and double panel construction. The windows without grating also provide a clear view of the machine inside.



Operator's Panel



The operator control panel is mounted on an adjustable pendant for easy viewing and accessibility during set-up and operation. The layout and location of the panel is ergonomically designed to be efficient and convenient for the operator Comprehensive alarm diagnostics are provided for the machine, control and programming errors.

Axis Drive Construction and Tail Stock

Double Pretensioned Ball Screw



Both the X and Z axes features a double pretensioned ball screw, supported on each end by precision class P4 angular contact thrust bearings. Both axes are driven by large diameter, high precision ball screws.

Programmable Tailstock

The programmable tailstock body is mounted on the same guideway surface as the headstock. The heavy casting, large 120mm (4.7 inch) diameter quill, and precision Morse Taper #6 live center provide outstanding rigidity. The 120mm (4.7 inch) quill stroke is activated by either the program or foot switch. Auto lubrication is provided to the quill and guideways.

Axis Drives



Each axis is powered by a maintenance free digital AC servo motor. These high torque drive motors are connected to the ball screws without intermediate gears for quiet and responsive slide movement with virtually no backlash.



Equipment

Collection of Waste Lubrication Oil

Less waste lubrication oil extends the life time of the coolant water and cut down the grime and offensive smell of the machine inside.

No Coolant Leakage

Rigorously designed, manufactured and tested machine covers do not permit coolant leakage in any condition. The factory always keeps our environment clean.

Hydraulic Power Unit

The temperature of the hydraulic oil is regulated by a cooling system.



Oil Skimmer @

The coolant is kept clean and its life is extended with bed casting channels from the Z axis to a separate reservoir. A belt oil skimmer picks up and removes waste oil from the coolant tank that is easily drained.



Metered Way Lubrication

Automatic lubrication is provided to all guideways, ball screws and the tailstock quill. A maintenance free piston distributor delivers a precise quantity of oil to each lubrication point. The 1.8 L (0.5 gallon) reservoir lasts up to 80 hours. A low level alarm prevents the machine from restarting without lubricant.



Tool Pre-Setter on

The automatic tool setter reduces setup time by minimizing the need for skim cuts, measurements and entering tool offsets.

The tool setting arm is moved by an electric motor and can be controlled through the program.



Electric Torque Limiters

Each axis ball screw is protected by electric torque limiters to minimize damage in the event of a crash. Upon impact, the limiter immediately stops the machine.

Long Boring Bar Holder 🐽



Coolant System

The high pressure flushes chips out of drilled holes, reduces the need for peck drill cycles, meets the requirements of most insert drill manufactures and significantly increases tool life.

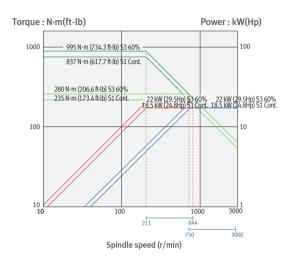
The separate, large 280[370] L (74[97.8] gallon) capacity coolant tank and chip pan are separate from the machine bed to prevent heat trans-fer and easy cleaning.

[]:Long bed

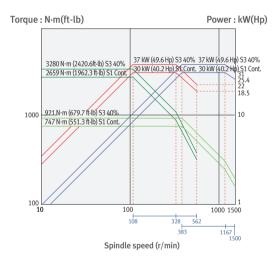


Main spindle power-torque diagram

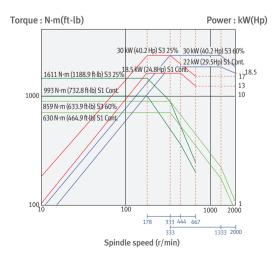
PUMA 400A/LA/XLA - 22kW (29.5 Hp) 30min



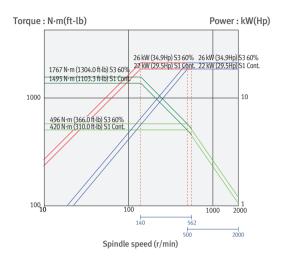
PUMA 400C/LC/XLC - 37 kW (49.6 Hp) 30min



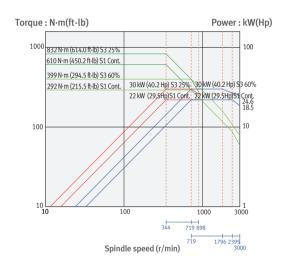
PUMA 400MB/LMB/XLMB - 30 kW (40.2 Hp) 30min



PUMA 400B/LB/XLB - 26 kW (34.9 Hp) 30min



PUMA 400MA/LMA/XLMA - 30 kW (40.2 Hp) 30min



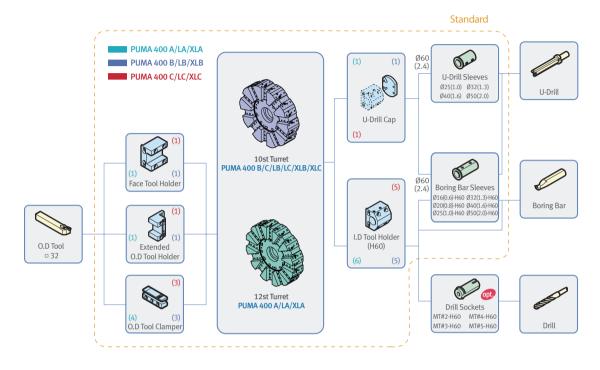
PUMA 400MC/LMC/XLMC - 37kW (49.6 Hp) 30min

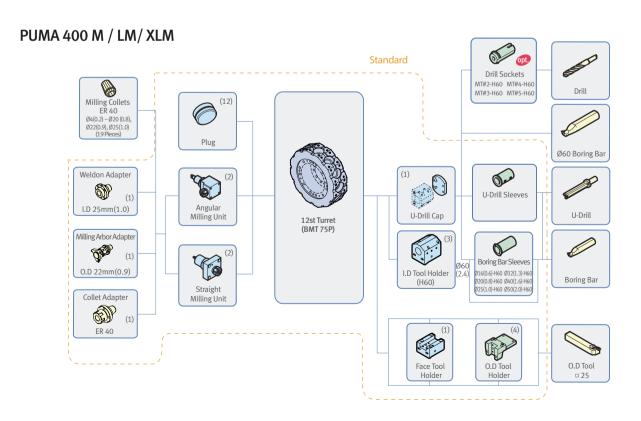


Tooling System

PUMA 400 A / B / C / LA / LB / LC / XLA / XLB / XLC

Unit: mm (inch)





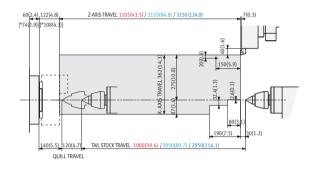
Working Range

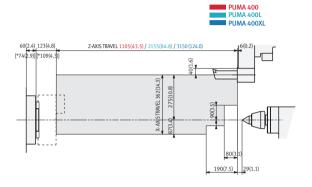
PUMA 400 / 400L / 400XL

Unit: mm (inch)

OD Tool Holder

ID Tool holder

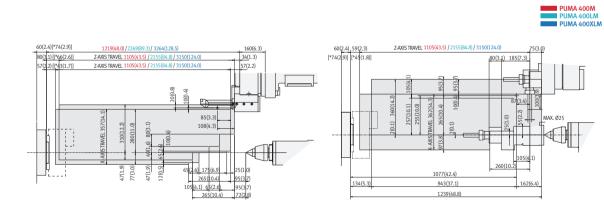




PUMA 400M / 400LM / 400XLM

OD/ID Tool Holder

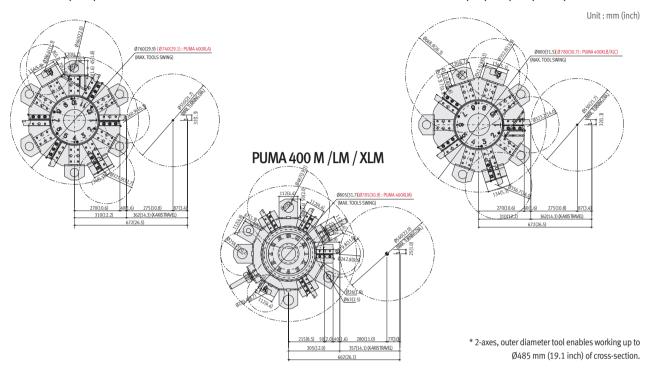
Straight//Angular milling unit



*: PUMA 400C

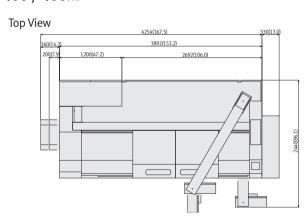
PUMA 400 A / LA / XLA

PUMA 400 B / C / LB / LC / XLB / XLC



External Dimensions

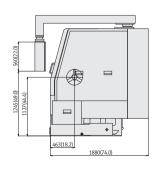
PUMA 400 / 400M



Front View

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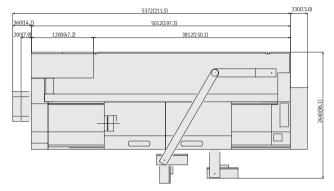
Side View



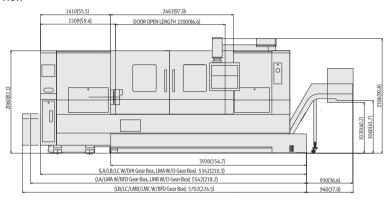
External Dimensions

PUMA 400L / 400LM

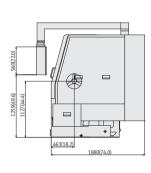
Top View
Unit: mm (inch)



Front View

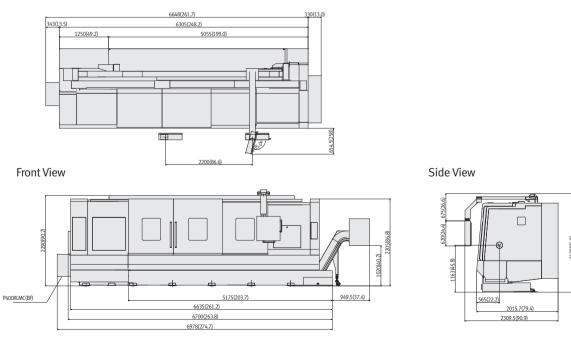


Side View



PUMA 400XL / 400XLM

Top View



Machine Specifications

	Features		Unit	PUMA 400A [LA]	PUMA 400B [LB]	PUMA 400C [LC]	PUMA 400MA [LMA]	PUMA 400MB [LMB]	PUMA 400MC [LMC]	PUMA 400XLA [XLB/XLC]	PUMA 400XLMA [XLMB/ XLMC]
	Swing over bed		mm (inch)				770 ((30.3)			
	Swing over saddle		mm (inch)	590 (23.2)							
	Recom. turning diameter		mm (inch)	305 (12.0) 380 (15.0)		305 (12.0) 380 (15.0)			305 [380] (12.0[15.0])		
Capacity	Max. turning diameter		mm (inch)	550 (21.7) 560 (22.0)			550 (21.7)	560 (22.0)			
	Max. turning length		mm (inch)	1079 [2129] (42.5 [83.8])	1043 [2093] (41.1 [82.4])	1024 [2074] (40.3 [81.7])	1014 [2064] (39.9 [81.3])	978 [2028] (38.5 [79.8])	959 [2009] (37.8 [79.1])		14 / 3095] 2.6 / 121.9])
	Bar working diam	eter	mm (inch)	90 (3.5)	117 (4.6)	165.5 (6.5)	90 (3.5)	117 (4.6)	165.5 (6.5)	_	90 [117 / 165.5] (3.5 [4.6 / 6.5])
	Travel distance	X-axis	mm (inch)		362 (14.3)			357 (14.1)		362 (14.3)	357 (14.1)
Carriage		Z-axis	mm (inch)	1105 [2155] (43.5 [84.8])				3150 (124.0)			
camage	Min. spindle Indexing angle (C-axis)		deg		-			360° {0.001°}			360° {0.001°}
Feedrate	Rapid traverse (X	/ Z)	m/min (ipm)		16 / 20	[16 / 18] (629.9	787.4 [629.9	/ 708.7])		16 / 10 (62	9.9 / 393.7)
	Chuck size		mm (inch)	305 (12.0)	380 (15.0)	530 (20.9)	305 (12.0)	380 (15.0)	530 (20.9)		[380 / 530] [15.0 / 20.9])
	Spindle speed		r/min	3000	2000	1500	3000	2000	1500	3000 [200	00 / 1500]
Main Spindle	Spindle nose		ASA	A2 - 8	A2 - 11	A1 - 15	A2 - 8	A2 - 11	A1 - 15	A2 - 8 [A2 - 11 / A1 - 15]	
	Spindle through hole		mm (inch)	102 (4.0)	132 (5.2)	181 (7.1)	102 (4.0)	132 (5.2)	181 (7.1)	102 [132 / 181] (4.0 [5.2 / 7.1])	
	Main spindle motor (Cont./30min)		kW (Hp)	18.5 / 22 (24.8 / 29.5)	22 / 26 (29.5 / 34.9)	30 / 37 (40.2 / 49.6)		(29.5 / 40.2) (40.2 / 49.6) (24.8 / 29.5 [29.5		18.5 / 22 [22 / 26, 30 / 37] (24.8 / 29.5 [29.5 / 34.9, 40.2 / 49.6])	22 / 30 [22 / 30, 30 / 37] (29.5 / 40.2 [29.5 / 40.2, 40.2 / 49.6])
Tool Post	No. of tool station		EA	12 {Base holder}		0 holder}	12 {BMT75P}		12 [10] {Base holder}	12 {BMT 75P}	
	Boring bar diameter		mm (inch)	60 (2.4)							
	Indexing time (1st	t swivel)	S			0.25 {1Station Swivel}					
Tail Stock	Quill diameter		mm (inch)				120	(4.7)			
Tall Slock	Quill bore taper						M	Г#6			
Power Source	Electric power sup (Rated capacity)	oply	kVA	35.5	43.0	53.1	48	58	3.1	35.5 [43.0/53.1]	48 [58.1]
Machine Size	Machine height		mm (inch)	2292 [2306]					2439		
	Machine size		mm (inch)	4582 x 2440 [5702 x 2440]				6978 x 2310			
	Machine weight		kg (lb)	9050 [10500] (19951.5 [23148.2])	9550 [11000] (21053.8 [24250.5])	10050 [11500] (22156.1 [25352.8])	9200 [10700] (20282.2 [23589.1])	9700 [11200] (21384.5 [24691.4])	10200 [11700] (22486.8 [25793.7])	11000 [11500 / 12000] (24250.5 [25352.8/26455.1])	11500 [12000/ 12500] (25352.8 [26455.1/27557.4)

Standard Feature

- Coolant supply equipment
- Foot switch
- Full enclosure chip and coolant shield
- \bullet Hand tool kit, including small hand tool for operations
- Hydraulic chuck & actuating cylinder
- Hydraulic power unit
- Leveling jack screw & plates
- Live center
- Lubrication equipment
- Soft jaws
- Standard tooling kit (tool holders& boring sleeves)
- Work light

Optional Feature

- Additional tool holders & sleeves
- Air blast for chuck
- Air gun
- Automatic door with safety device
- Automatic measuring system (in process touch probe)
- Automatic power off
- Automatic work loading & unloading equipment
- Bar feeder interface
- Chip bucket
- Chip conveyor

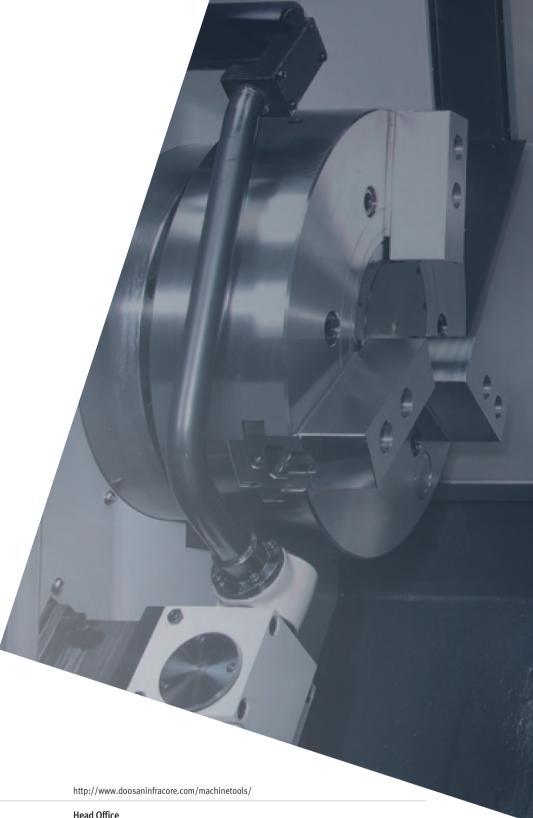
- Controller : Fanuc 31i-A
- Dual chucking pressure
- Hardened & ground jaws
- Hydraulic steady rest
- Manual steady rest
- Long boring bar (ø 100)
- Oil skimmer
- Pressure switch for chucking pressure check
- Programmable tail stock

NC Unit Specifications

Item	Controls			
- Controlled axes	Item	Spec.		Fanuc i
Axis Functions			X, Z, C (!)	
- Backlash compensation	- Simultaneously controlled axes	Std. 2 axes	3 axes(!)	3 axes(!)
- Backlash compensation				
- Cs contouring control				
- Follow-up / Chamfering on/off		0~±9999 pulses		
-HRV2 control -Increment system 1/10 -Increment stroke check 1 -Increment system 1/10 -Incr			- '/	
-Increment system 1/10				
Operation - Stored stroke check 1 Overtravel control O - Stored stroke check 2, 3 Overtravel control O - Stored stroke check 2, 3 Overtravel control O - Stored stroke check 2, 3 Overtravel control O - Stored stroke check 2, 3 Overtravel control O - Interpolation - 1st. reference position return G30 O - Automatic operation (memory) / Buffer register - Circular interpolation G02 O - Automatic operation (memory) / Buffer register - Circular interpolation G02 O - Dwell (per sec) G04 O - Handle incremental feed X1, X10, X100 O - Handle incremental feed X1, X10, X100 O - Multiple threading / Thread cutting retract - Polar coordinate interpolation O(I) O(I) - Search function Sequence NO. / Program NO. - Thread cutting / Synchronous cutting - Feed Functions - Feed per minute / Feed per revolution - Feed a verride O - 200% (10% unit) O - Rapid traverse override F0 / 25 / 100 % O - Tangential speed constant control - Axuiliary & Spindle Functions - Constantant surface speed control O - Multi-spindle control O(I) O(I) - Multi-spindle control O(I) O(I) - Spindle orientation O(I) O(I) - Spindle serial output S4 / S5 digits O - Spindle speed override O-150% O - Programming Functions - Absolute / Incremental programming / O - Decimal point programmi				
- Stored stroke check 1 Overtravel control O O O Stored stroke check 2, 3 Overtravel control O O O O O O O O O O O O O O O O O O O	- Least input increment		0	0
- Stored stroke check 1 Overtravel control O O O Stored stroke check 2, 3 Overtravel control O O O O O O O O O O O O O O O O O O O	Operation			
Stored stroke check 2, 3	- Stored stroke check 1	Overtravel control	0	
Interpolation -1st. reference position returm				
-1st. reference position returm				
-1st. reference position returm	Interpolation			
- Automatic operation (memony) / Buffer register		Manual, G28	0	0
Buffer register - Circular interpolation		G30	0	0
- Circular interpolation G02 O O O Continuous thread cutting O O O O O O O O O O O O O O O O O O O			0	0
- Dwell (per sec) G04 O O - Handle incremental feed X1, X10, X100 O O - Linear interpolation G01 O O - Multiple threading / Thread cutting retract O O (!) O(!) - Search function Sequence NO. / Program NO Thread cutting / Synchronous cutting O O O - Thread cutting / Synchronous Cutting O O O O - Thread cutting / Synchronous Cutting O O O O O O O O O O O O O O O O O O O		G02	0	0
- Handle incremental feed X1, X10, X100 O O - Linear interpolation G01 O O - Multiple threading / Thread cutting retract O O O - Multiple threading / Thread cutting retract O O O - Polar coordinate interpolation O (!) O (!) - Search function Sequence NO. / Program NO Thread cutting / Synchronous O O O - Thread cutting / Synchronous O O O - Thread cutting / Synchronous O O O - Thread cutting / Synchronous O O O O O O O O O O O O O O O O O O O	- Continuous thread cutting		0	0
- Linear interpolation G01 O O - Multiple threading / Thread cutting retract O O O - Polar coordinate interpolation O (!) O (!) O (!) - Search function Sequence NO. / Program NO Thread cutting / Synchronous O O O - Thread cutting / Synchronous O O O - Thread cutting / Synchronous O O O O - Thread cutting / Synchronous O O O O O O O O O O O O O O O O O O O			0	0
- Multiple threading / Thread cutting retract - Polar coordinate interpolation - Search function - Search function - Search function - Thread cutting / Synchronous cutting - Thread cutting / Synchronous cutting - Feed Functions - Feed per minute / Feed per revolution - Feed revolution - Feedrate override - O - 200% (10% unit) - Jog feed override - O - 2000 mm/min - Rapid traverse override - Fo / 25 / 100 % - Tangential speed constant control - Constantant surface speed control - M-function - Multi-spindle control - Multi-spindle control - Multi-spindle control - Spindle orientation - Spindle serial output - Spindle speed override - O - Spindle speed override - Constantant surface speed control - Spindle serial output - Spindle speed override - Spindle speed override - Constantant surface speed control - Constantant surface speed control - Multi-spindle control - Multi-spindle control - Spindle serial output - Spindle serial output - Spindle speed override - Constantant surface speed control - Constantant surface speed control - Spindle speed override - Constantant surface speed control - Spindle speed override - Constantant surface speed control - Custom macro	- Handle incremental feed	X1, X10, X100	0	0
retract - Polar coordinate interpolation - Search function - Search function - Thread cutting / Synchronous cutting - Feed Functions - Feed per minute / Feed per revolution - Feed revolution - Feedrate override - O - 200% (10% unit) - Jog feed override - O - 2000 mm/min - Rapid traverse override - Fo / 25 / 100 % - Tangential speed constant control - Constantant surface speed control - M-function - Multi-spindle control - Multi-spindle control - Spindle orientation - Spindle serial output - Spindle speed override - O - 2500 mm/min - O - O - Multi-spindle control - Molti-spindle control - Spindle serial output - Spindle serial output - Spindle speed override - O - 2000 mm/min - O - O - Multi-spindle control - Molti-spindle control - Spindle serial output - Spindle serial output - Spindle serial output - Spindle speed override - O - 2000 mm/min - O - 0 - O - 2000 mm/min - O - 0 - O		G01	0	0
- Search function Sequence NO. / Program NO. - Thread cutting / Synchronous cutting - Feed Functions - Feed Functions - Feed per minute / Feed per revolution - Feed active override - Jog feed override - Jog feed override - Rapid traverse override - Rapid traverse override - Tangential speed constant control - Axuiliary & Spindle Functions - Constantant surface speed control - M-function - Multi-spindle control - Multi-spindle control - Multi-spindle control - Multi-spindle control - Spindle serial output - Spindle serial output - Spindle speed override - Spindle speed override - Constantant surface Speed control - Constantant surface Speed control - Malti-spindle control - Multi-spindle control - Multi-spindle control - Spindle serial output - Spindle serial output - Spindle speed override - Spindle speed override - Constantant Surface - Constantant Surface Speed control - Control Speed Control Speed Control - Control Speed Control - Control Speed Control Speed Control Speed Control Speed Cont			0	0
Feed Functions - Feed per minute / Feed per revolution - Feed per minute / Feed per revolution - Feed override - Jog feed override - Jog feed override - Rapid traverse override - Tangential speed constant control Axuiliary & Spindle Functions - Constantant surface speed control - Multi-spindle control - Multi-spindle control - Multi-spindle control - Spindle orientation - Spindle serial output - Spindle speed override - Absolute / Incremental programming - Canned cycle for drilling / Turming - Custom macro - Decimal point programming /	- Polar coordinate interpolation		0 (!)	0 (!)
revolution Feed Functions - Feed per minute / Feed per revolution - Feedrate override - Jog feed override - Rapid traverse override - Rapid traverse override - Tangential speed constant control - Tangential speed constant control - Tangential speed constant control - Constantant surface speed control - M-function - M-function - Ma digits - Multi-spindle control - Multi-spindle control - Multi-spindle control - Multi-spindle control - Spindle orientation - Spindle serial output - Spindle speed override - Spindle speed override - Spindle speed override - Constantant surface speed control - Cultoma for the speed control - Constantant surface speed	- Search function		0	
- Feed per minute / Feed per revolution - Feedrate override - Jog feed override - Rapid traverse override - Tangential speed constant control - Constantant surface speed control - Multi-spindle control - Multi-spindle control - Multi-spindle control - Multi-spindle control - Spindle serial output - Spindle serial output - Spindle speed override - Spindle speed override - Constantant surface speed control - Multi-spindle control - Multi-spindle control - Multi-spindle control - Spindle orientation - Spindle serial output - Spindle serial output - Spindle speed override - Spindle speed override - Constantant surface speed control - Spindle serial output - Spindle serial output - Spindle serial output - Spindle speed override - Constantant surface speed control - Constantant s			0	0
- Feed per minute / Feed per revolution - Feedrate override - Jog feed override - Rapid traverse override - Tangential speed constant control - Constantant surface speed control - Multi-spindle control - Multi-spindle control - Multi-spindle control - Multi-spindle control - Spindle serial output - Spindle serial output - Spindle speed override - Spindle speed override - Constantant surface speed control - Multi-spindle control - Multi-spindle control - Multi-spindle control - Spindle orientation - Spindle serial output - Spindle serial output - Spindle speed override - Spindle speed override - Constantant surface speed control - Spindle serial output - Spindle serial output - Spindle serial output - Spindle speed override - Constantant surface speed control - Constantant s	Feed Functions			
revolution Feedrate override Foedrate override O-200% (10% unit) Foedrate override O-2000 mm/min O Rapid traverse override Fo / 25 / 100 % O Tangential speed constant control Axuiliary & Spindle Functions Constantant surface speed control M3 digits O Multi-spindle control Rigid tapping O Multi-spindle control O(!) Spindle orientation Spindle serial output Square Spindle Square Spindle speed override Programming Functions Absolute / Incremental programming Canned cycle for drilling / Turning GO1 Custom macro D O O O O O O O O O O O O				
- Jog feed override 0 - 2000 mm/min 0 0 - Rapid traverse override F0 / 25 / 100 % 0 0 - Tangential speed constant control 0 0 Axuiliary & Spindle Functions - Constantant surface speed control 0 0 0 - M-function M3 digits 0 0 - Multi-spindle control 0 0 (!) 0 (!) - Rigid tapping 0 0 0 - Multi-spindle control 0 0 (!) 0 (!) - Spindle orientation 0 0 0 - Spindle serial output S4 / S5 digits 0 0 - Spindle speed override 0 0 0 - Spindle speed override 0 0 0 Programming Functions - Absolute / Incremental programming G01 0 0 - Custom macro G01 0 0 - Decimal point programming / 0 0	revolution			
- Rapid traverse override F0 / 25 / 100 % O O Tangential speed constant control O O - Tangential speed constant control O O O - Axuiliary & Spindle Functions - Constantant surface speed control O O O O O O O O O O O O O O O O O O O				
- Tangential speed constant control Axuiliary & Spindle Functions - Constantant surface speed control - M-function M3 digits O Multi-spindle control - Spindle orientation - Spindle serial output - Spindle speed override - Spindle speed override - Spindle speed override - Canned cycle for drilling / Turning - Custom macro - Decimal point programming /	7 0			
Axuiliary & Spindle Functions - Constantant surface speed control O O - M-function M3 digits O O - Multi-spindle control O(!) O(!) - Rigid tapping O O - Multi-spindle control O(!) O(!) - Spindle orientation O O - Spindle serial output S4 / S5 digits O O - Spindle speed override O~150% O O Programming Functions - Absolute / Incremental programming G01 O O - Custom macro G01 O O - Decimal point programming /		F0 / 25 / 100 %		
- Constantant surface speed control - M-function M3 digits O - Multi-spindle control Rigid tapping - Multi-spindle control - Multi-spindle control - Multi-spindle control - Multi-spindle control - Spindle orientation - Spindle serial output - Spindle serial output - Spindle speed override - Spindle speed override - Spindle speed override - Spindle speed override - Control Spindle	- langential speed constant control		0	0
- Constantant surface speed control - M-function M3 digits O - Multi-spindle control Rigid tapping - Multi-spindle control - Multi-spindle control - Multi-spindle control - Multi-spindle control - Spindle orientation - Spindle serial output - Spindle serial output - Spindle speed override - Spindle speed override - Spindle speed override - Spindle speed override - Control Spindle	Axuiliary & Spindle Function	15		
- Multi-spindle control O(!) O(!) - Rigid tapping O O - Multi-spindle control O(!) O(!) - Spindle orientation O O - Spindle serial output S4 / S5 digits O O - Spindle speed override O~150% O O - Spindle speed override O~150% O O - Constant of the first of the spindle speed override O O O O O O O O O O O O O O O O O O O			0	0
- Rigid tapping O O - Multi-spindle control O(!) O(!) - Spindle orientation O O - Spindle serial output S4 / S5 digits O O - Spindle speed override 0~150% O O - Spindle speed override 0~150% O O - Spindle speed override 0~150% O O - Custom macro G01 O O - Decimal point programming / O O		M3 digits	0	0
- Multi-spindle control O(!) O(!) - Spindle orientation O O - Spindle serial output S4 / S5 digits O O - Spindle speed override 0~150% O O Programming Functions - Absolute / Incremental programming G01 O O - Canned cycle for drilling / Turning G01 O O - Custom macro G01 O O - Decimal point programming / O O			0 (!)	0 (!)
- Spindle orientation O O - Spindle serial output \$4 / \$5 digits O O - Spindle speed override 0~150% O O Programming Functions - Absolute / Incremental programming G01 O O - Canned cycle for drilling / Turning G01 O O - Custom macro G01 O O - Decimal point programming / O O				
- Spindle serial output \$4 / \$5 digits \$0 \$0 - Spindle speed override \$0 ~ 150% \$0 \$0 Programming Functions - Absolute / Incremental programming \$601 \$0 \$0 - Canned cycle for drilling / Turning \$601 \$0 \$0 - Custom macro \$601 \$0 \$0 - Decimal point programming / \$0 \$0				
- Spindle speed override 0~150% O O Programming Functions - Absolute / Incremental programming G01 O O - Canned cycle for drilling / Turning G01 O O - Custom macro G01 O O - Decimal point programming / O O		C . / C = 1: ::		
Programming Functions - Absolute / Incremental programming G01 O O - Canned cycle for drilling / Turning G01 O O - Custom macro G01 O O - Decimal point programming / O O				
- Absolute / Incremental programming G01 O O - Canned cycle for drilling / Turning G01 O O - Custom macro G01 O O - Decimal point programming / O O	- Spinale speed override	U~15U%	O	<u> </u>
programming - Canned cycle for drilling / Turning G01 O O - Custom macro G01 O O - Decimal point programming / O O	Programming Functions			
- Canned cycle for drilling / Turning G01 O O - Custom macro G01 O O - Decimal point programming /		G01	0	0
- Custom macro G01 O O - Decimal point programming /		G01	0	0
	- Custom macro	G01	0	0
		programming	0	0

Item	Spec.	Fanuc 32i-A	Doosar Fanuc i series	
- Direct drawing dimension programming		0	0	
- eZ Guide i	Conversational programming	0	Opt.	
- Maximum program dimension	±9 digits	0	0 (!)	
- Multi repetitive canned cycle	G70~G76	0	0	
- Multi repetitive canned cycle 2		0	0	
- Optional block skip (without hardware)	Total 9 (Only NC function)	0	0	
- Programmable data input	G10	0	0	
- Sequence number		N8	N5	
- Sub program call	Nested holds	10	4	
- Tape format for FANUC series 10/11		_	0	
· Work coordinate system	G52~G59	0	0	
Tool Functions				
- Auto tool offset		0	0	
Direct input of tool offset value measured B		0	0	
- Tool geometry / wear compensation	Geometry & wear data	0	0	
- T-code function	T2+2 digits	0	0	
· Tool life management	-	0	0	
Tool load monitoring system		Opt.	_	
Tool nose radius compensation		0	0	
· Tool offset pairs		64pairs	64paiı	
- Tool offset value counter input		0	0	
Editing Op. Functions Background editting	Copy, Move,	0	0	
- Expanded part program editting	Change of NC program	0	0	
- No. of Registered programs		500ea	400ea	
Dart program aditing / Dragram		0	0	
protect				
protect		640m		
protect Part program storage length* Setting & Display				
Part program storage length* Setting & Display Display of spindle speed and				
protect Part program storage length* Setting & Display Display of spindle speed and T-code at all screen	Alarm & Operation display	640m	1280r	
Part program storage length* Setting & Display Display of spindle speed and T-code at all screen Help function		640m	1280r	
protect Part program storage length* Setting & Display Display of spindle speed and T-code at all screen Help function Self diagnostic function		640m O	0 0	
protect Part program storage length* Setting & Display Display of spindle speed and T-code at all screen Help function Self diagnostic function Servo setting screen / Spindle setting screen		640m O O	0 0	
protect Part program storage length* Setting & Display Display of spindle speed and T-code at all screen Help function Self diagnostic function Servo setting screen / Spindle setting screen Data Input & Output	display	640m O O	0 0	
protect Part program storage length* Part program storage length* Setting & Display Display of spindle speed and T-code at all screen Help function Self diagnostic function Servo setting screen / Spindle setting screen Data Input & Output 1/O interface		640m O O O (I)	0 0 0	
protect Part program storage length* Part program storage length* Setting & Display Display of spindle speed and T-code at all screen Help function Self diagnostic function Servo setting screen / Spindle setting screen Data Input & Output I/O interface Memory card input and output	display	640m O O O (!)	1280r	
protect Part program storage length* Part program storage length* Setting & Display Display of spindle speed and T-code at all screen Help function Self diagnostic function Servo setting screen / Spindle setting screen Data Input & Output I/O interface Memory card input and output Reader puncher control	display	640m O O O O(!)	0 0 0	
protect Part program storage length* Part program storage length* Setting & Display Display of spindle speed and T-code at all screen Help function Self diagnostic function Servo setting screen / Spindle setting screen Data Input & Output I/O interface Memory card input and output Reader puncher control Spindle speed override	display RS-232C	640m O O O O(!)	0 0 0	
Part program storage length* Setting & Display Display of spindle speed and T-code at all screen Help function Self diagnostic function Servo setting screen / Spindle	display	640m O O O (!)	1280r	
protect Part program storage length* Part program storage length* Display Display of spindle speed and T-code at all screen Help function Self diagnostic function Servo setting screen / Spindle setting screen Data Input & Output I/O interface Memory card input and output Reader puncher control Spindle speed override Other Functions	RS-232C Embedded ethernet	640m O O O O O O O O O O O O O O O O O O	1280r	

O: Standard OPT: Option (!): only M type
*1: Standard Part program length is different on export condition. On the addition of optional functions, its length can be reduced.





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⁻ The specifications and information above-mentioned may be changed without prior notice. - For more details, please contact Doosan.



